

# Nhan (Nick) Phan

## Mechanical Engineering Student in Hamilton, Ontario

- A 3<sup>rd</sup>-year Mechanical Engineering at McMaster University seeking an internship starting May 2020
- Designed multiple rocket models and troubleshoot structural issues for the McMaster Rocketry Team
- Constructed an improved Mars Rover chassis for the McMaster Mars Rover Team
- Played a key role in organizing the Ontario Rover Rally in the summer of 2019

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647-708-0305 — [phann6@mcmaster.ca](mailto:phann6@mcmaster.ca) — <https://nick-5-3.github.io>

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## PROFESSIONAL EXPERIENCE

**McMaster Mars Rover Team** Hamilton, Ontario  
**Manufacturing Specialist** 09/2019 - present

- Designed and developed more stable chassis for the working Mars rover prototype
- Machined wooden parts for a Rover prototype based on technical sketches using the bandsaw, drill press, and various hand tools
- In-depth collaboration with design team members on GrabCAD Workbench

**McMaster Rocketry Team** Hamilton, Ontario  
**Structural Team Lead** 08/2019 - present

- Led the structural team to design and construct C-class rocket models as prototypes for the G-class sounding rocket
- Modeled and constructed finite element analysis (FEA) on multiple versions using Autodesk Fusion 360 and SolidWorks
- Created technical drawings of parts in accordance with ASME Y14.5 GD&T standards
- Improved rocket efficiency by reducing the weight of 3D printed parts by 40%, allowing more space for avionics
- Set up a launch simulation of the design using Simulink and thrust data provided by the motor manufacturer, Estes
- Currently attempting to implement a 3D-printed thrust vectoring system for the C-class rocket

## EDUCATION

**McMaster University** Hamilton, Ontario  
**Bachelor of Engineering: Mechanical** 09/2018 - 04/2023

- Courses: Mechanics, Manufacturing Engineering, Statics of Materials, Dynamics of Materials, Thermodynamics

## Online Courses

- Autodesk Fusion 360 Integrated CAD/CAM/CAE on Coursera
- 3D Model Creation with Autodesk Fusion 360 on Coursera
- Engineering Design Process with Fusion 360 on Coursera
- MATLAB Onramp
- Simulink Onramp

## VOLUNTEER EXPERIENCE

**Ontario Rover Rally**  
05/2019 – 08/2019

Provides a risk-free event for Rover teams to test out their creations and generate excitement for space

- Raised funds and obtained swag through contact with 3 main sponsors
- Managed small-scale logistics and made purchases to make sure the event runs smoothly
- Worked 12 hours a day for 2 weeks to build an obstacle course for the event's Rover Race

## PROJECTS

### Robot Arm

05/2020

Developing a 3D-printed robot arm with 9g hobby servos to study inverse kinematics

### Self-Feeding Catheter

01/2020

Received 3<sup>rd</sup> place overall in the 2020 McMaster Designathon

- In a team of 4, designed a semi-automatic implementation of the Seldinger technique for catheter insertion

### Sumobot

11/2019

- Designed, built, and programmed an autonomous sumo robot